

A Hand-on Tutorial on NeRF for XR Applications

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T2: A PRACTICAL GUIDE TO RADIANCE FIELDS FOR XR RESEARCH AND APPLICATIONS



Agenda

- Brief introduction to NeRF
- Brief introduction to instant-ngp
- Introduction to immersive-ngp
- Live tutorial on immersive-ngp toolkit
 - \circ Scene rendering in VR
 - o Interaction & editing
 - o Performance consideration



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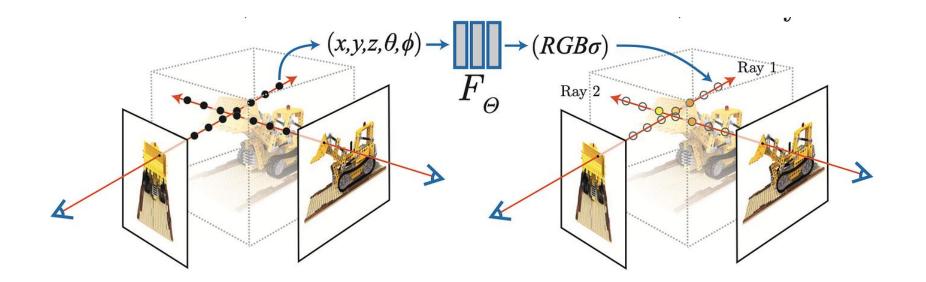


Neural Radiance Fields (NeRF)



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Neural network can learn from 2D images through gradient descent, therefore, **compressing** the 3D scene representation to a small scene function.



Mildenhall, B., Srinivasan, P.P., Tancik, M., Barron, J.T., Ramamoorthi, R., & Ng, R. (2020). NeRF. Communications of the ACM, 65, 99 - 106.

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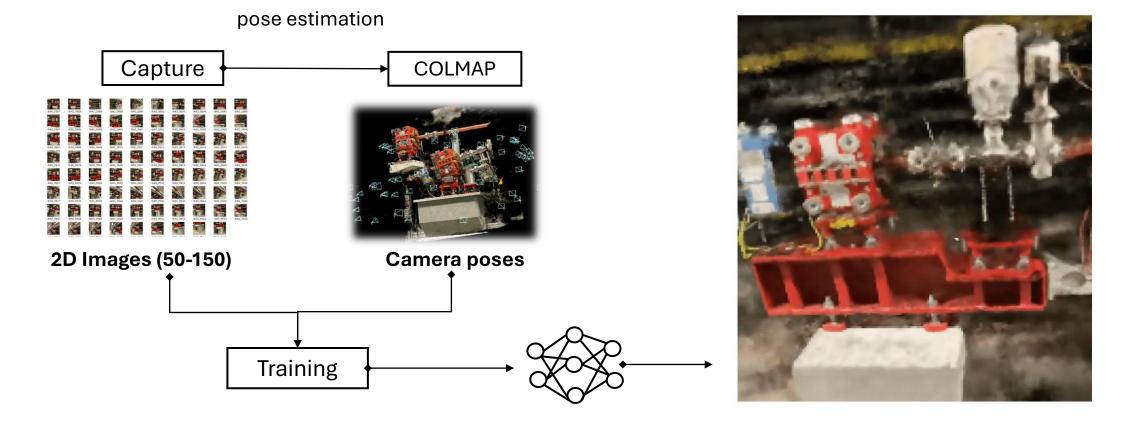




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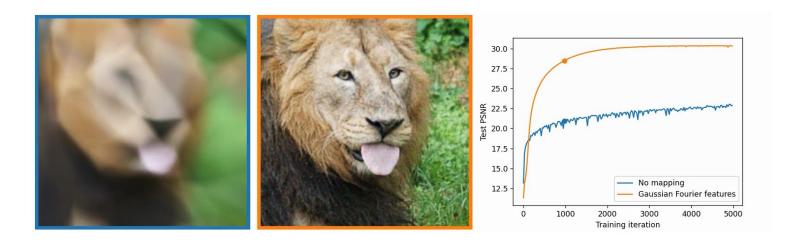
Neural Radiance Fields (NeRF) Generation







Positional Encoding: the Key to NeRF's Success



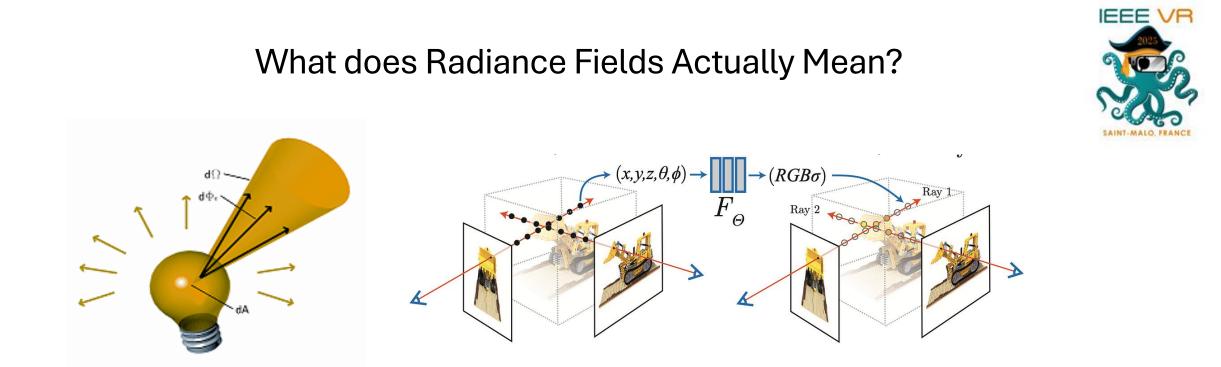
- Neural networks tend to have a bias against low frequency functions
 - But most image details are high frequency features (like fine surfaces, sharp edges, or order small-scale variations, reflections, etc)
 - Apply a fourier feature network to the input position p to transform it to high dimensional space

$$\gamma(p) = \left(\sin\left(2^0\pi p\right), \cos\left(2^0\pi p\right), \cdots, \sin\left(2^{L-1}\pi p\right), \cos\left(2^{L-1}\pi p\right)\right)$$









Radiance characterizes how a surface emit, reflect, transmit, or absorb light.

In NeRF, it characterizes how each point in the scene emits light (e.g, which color is the light, at what intensity/opacity) at different viewing angles











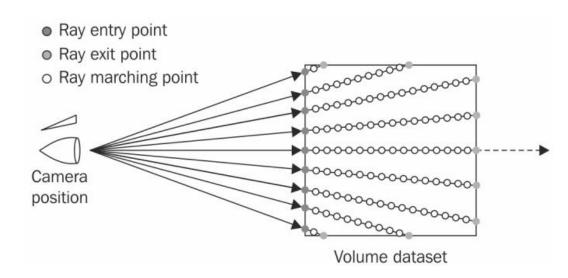
IEEE VR

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How is NeRF rendered?



NeRF can be rendered through the classic volume rendering equation lacksquare

$$C(\mathbf{r}) = \int_{t_n}^{t_f} T(t) \sigma(\mathbf{r}(t)) \mathbf{c}(\mathbf{r}(t), \mathbf{d}) dt \,, \text{ where } T(t) = \exp \biggl(-\int_{t_n}^t \sigma(\mathbf{r}(s)) ds \biggr)$$

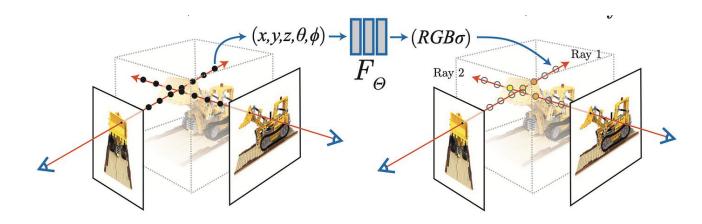
with r(t) = ray point at distance t, d = view-direction,

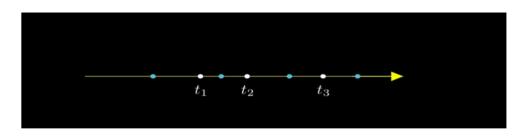
 $\sigma(x) = density, c(x) = color$



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Volume Rendering through NeRF can be Super Expensive!





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$$P_{(h,w)} = R_h \times R_w \times N_{\boldsymbol{r}(t)} \times \overline{F}$$

spacial-temporal trade off A high resolution image can take > 30s to render!

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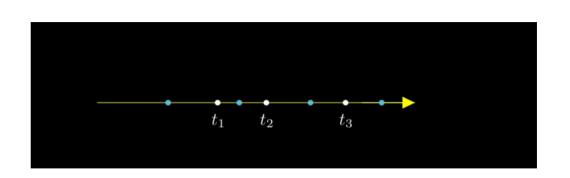
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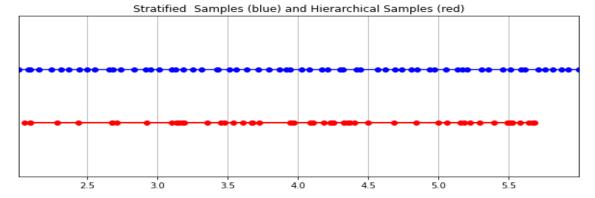
Hierarchical Sampling



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- We don't want to evenly sample every ray
 - Adjust the density of the sample points based on the required level of detailed





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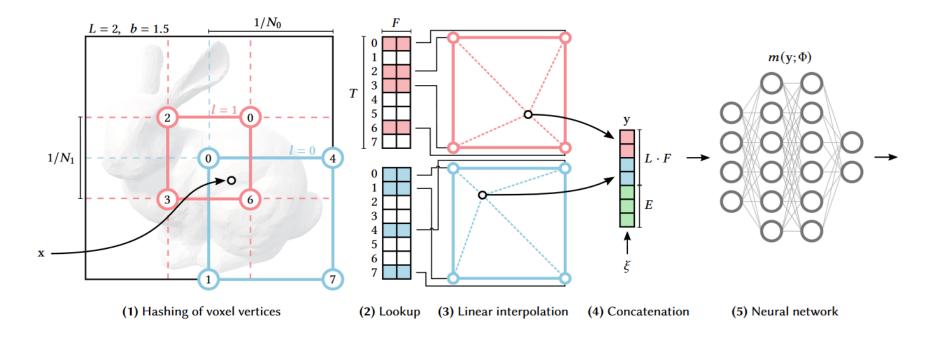
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Instant Neural Graphics Primitives (Instant ngp)

• Learn a multi-resolution positional encoding instead of precomputing it



Müller, T., Evans, A., Schied, C., & Keller, A. (2022). Instant neural graphics primitives with a multiresolution hash encoding. ACM Transactions on Graphics (TOG), 41, 1 - 15.



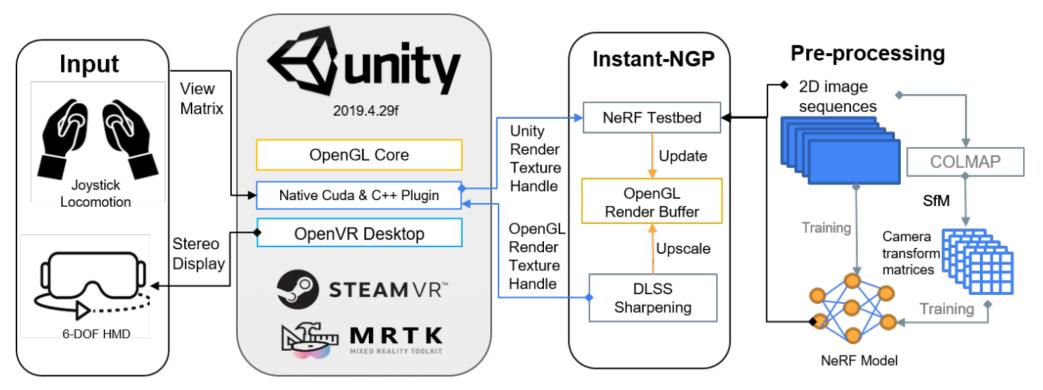
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Immersive-ngp



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¹ K.Li*, T.Rolff*, S. Schmidt, R.Bacher, W.Leemans, S.Frintrop, F.Steinicke:Bringing Instant Neural Graphics Primitives to Immersive Virtual Reality, IEEE Conference on Virtual Reality and 3D User Interfaces (IEEE VR) 2023, (2 pages)

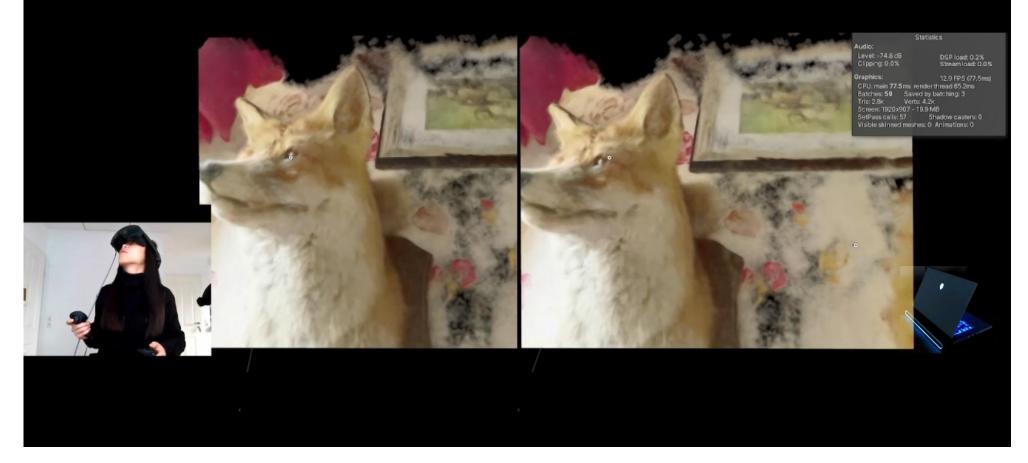






Rendering NeRF in immersive VR

Note: All the following videos run on an Allenware laptop and a Meta Quest Pro



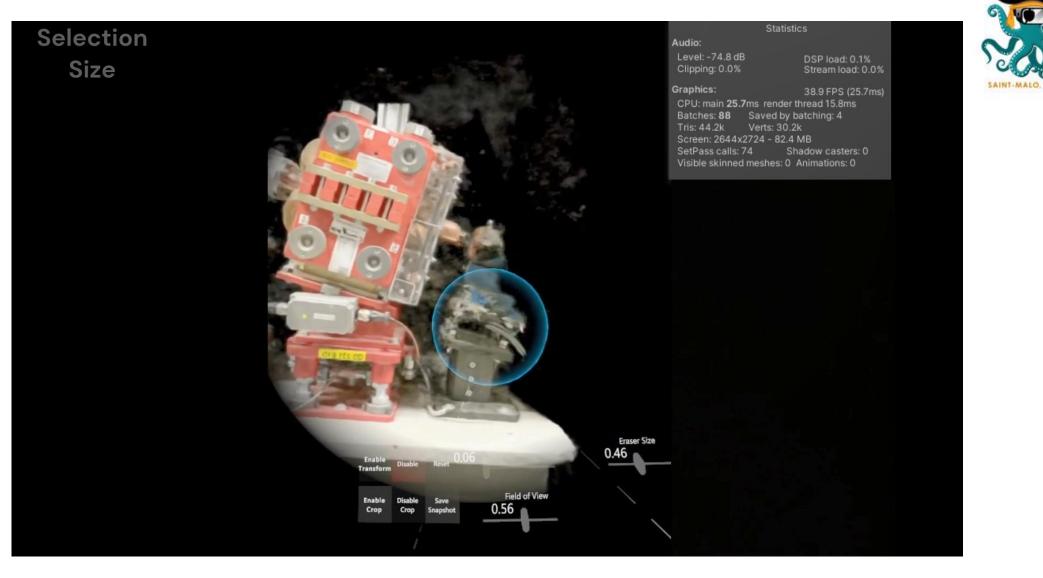
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Voxel-wise 3D Edition on NeRF¹







IEEE VR

Interactive Contextual Visualization





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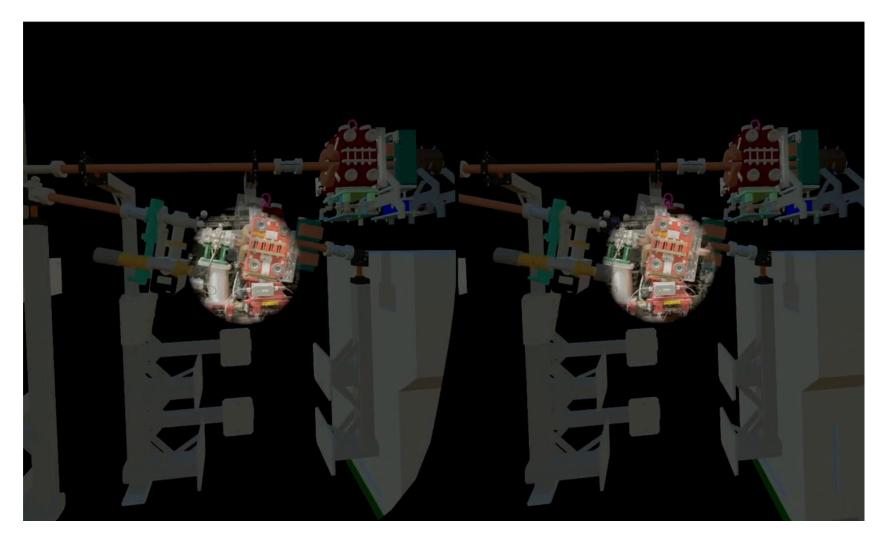


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Magic NeRF Lens Effects



Li, Ke et al. "Magic NeRF Lens: Interactive Fusion of Neural Radiance Fields for Virtual Facility Inspection." *ArXiv* abs/2307.09860 (2023)

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Live Demo

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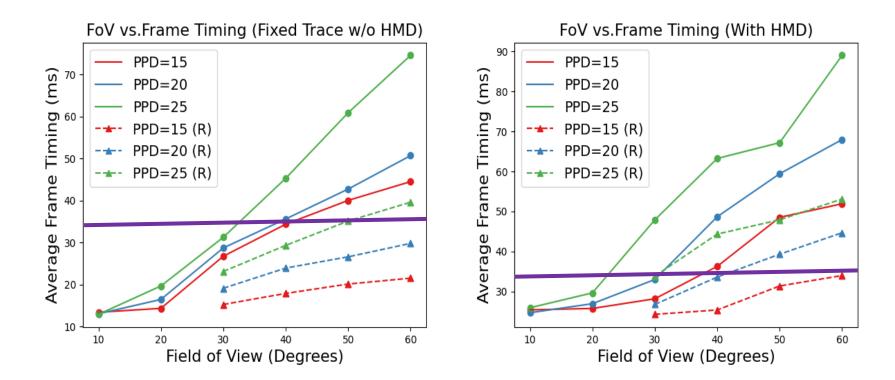




Performance benchmark



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Optimal configuration at one-to-one real-world size is **20 PPD at 30° FoV**, **15 PPD at 40° FoV** (RTX 3090 GPU)

Li, Ke et al. "Magic NeRF Lens: Interactive Fusion of Neural Radiance Fields for Virtual Facility Inspection." ArXiv abs/2307.09860 (2023)

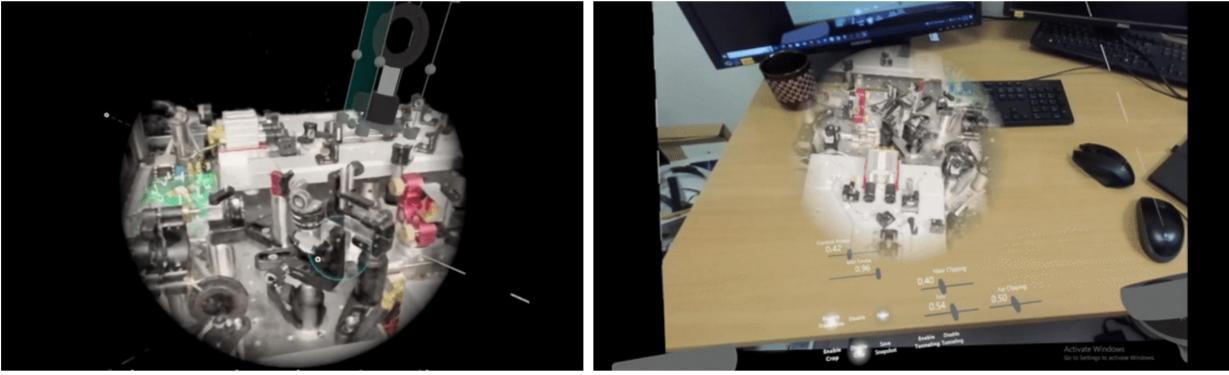
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NeRF in Immersive MR¹





1. K Li, T.Rolff, R.Bacher, F.Steinicke: RealityGit: Cross Reality Version Control of R&D Optical Workbench, at IEEE International Symposium on Mixed and Augmented Reality Adjunct (ISMAR-Adjunct) 2023 (2 pages)

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NeRF limitation



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- Interoperability: Limited compatibility with standard 3D tools/pipelines.
- High Compute Cost: Resource-heavy volumetric rendering.
- Limited interactbility: Implicit representation complicates geometry-based editing & interaction.
- **Sparse View Artifacts**: Hallucinates details with insufficient input views.
- **Pose Sensitivity**: Requires precise camera calibration; errors degrade quality.



