

IEEE VR



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A Practical Guide to Radiance Fields for XR Research and Applications

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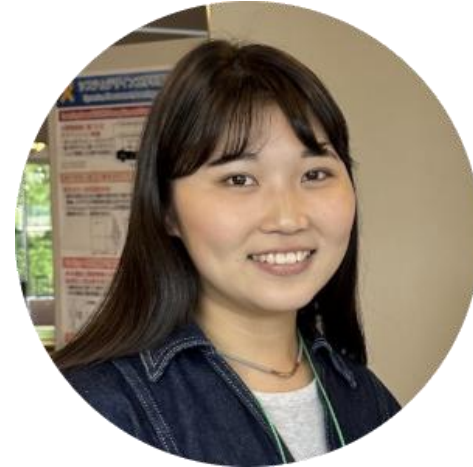
Team



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PROGRAM

08:30 - 08:40 **Opening and Welcoming**

08:40 - 09:00 **Introduction to Radiance Fields for XR (PDF)**

Shohei Mori presents the basics of NeRF and 3DGS, and how they have evolved view synthesis compared to conventional image-based rendering approaches.

09:00 - 09:25 **Live Tutorial on NeRF for VR (PDF)**

Ke Li presents details of NeRF and [immersive-ngp](#), demonstrating how to get a NeRF model in Unity and VR.

09:25 - 09:50 **Live Tutorial on 3DGS for VR (PDF)**

Mana Masuda presents details of 3DGS and [UnityGaussianSplatting](#), demonstrating how to get 3DGS in Unity and VR.

09:50 - 10:15 **Interactive Discussion - Future Challenges in XR**

Shohei Mori gives a summary and shares challenges for future XR research using NeRF and 3DGS.

We also welcome the following three short presentations from the main conference:

- "Semantics-Controlled Gaussian Splatting for Outdoor Scene Reconstruction and Rendering in Virtual Reality", Hannah Schieber (TUM)
- "Multi-Layer Gaussian Splatting for Immersive Anatomy Visualization", Constantin Kleinbeck (TUM)
- "DimSplat: A Real-Time Diminished Reality System for Revisiting Environments Using Gaussian Splats in Mobile WebXR", Kristoffer Waldow (TH Köln)

We welcome all attendees to an interactive discussion and exchange.



Radiance Fields at VR 2025

Papers & Keynote



Monday

- 09:45-10:45 | **Keynote** | The 3D Gaussian Splatting Adventure: Past, Present and Future
- 11:15-12:15 | GaussianHand: Real-Time 3D Gaussian Rendering for Hand Avatar
- 11:15-12:15 | SplatLoc: 3D Gaussian Splatting-based Visual Localization for Augmented Reality

Tuesday

- 08:30-09:30 | Look at the Sky: Sky-aware Efficient 3D Gaussian Splatting in the Wild
- 11:15-12:15 | **Semantics-Controlled Gaussian Splatting for Outdoor Scene Reconstruction and Rendering in Virtual Reality** by Hannah Schieber, *et al.* 🍌
- 11:15-12:15 | Frequency-aware Uncertainty Gaussian Splatting for Dynamic Scene Reconstruction
- 17:15-18:15 | SRBF-Gaussian: Streaming-Optimized 3D Gaussian Splatting
- 17:15-18:15 | MPGS: Multi-plane Gaussian Splatting for Compact Scenes Rendering

Wednesday

- 08:30-09:30 | GO-NeRF: Generating Objects in Neural Radiance Fields for Virtual Reality Content Creation
- 15:15-16:15 | 360o 3D Photos from a Single 360o Input Image
- 15:15-16:15 | Fov-GS: Foveated 3D Gaussian Splatting for Dynamic Scene
- **15:15-16:15 | Multi-Layer Gaussian Splatting for Immersive Anatomy Visualization** by Constantin Kleinbeck, *et al.* 🍌

Radiance Fields at VR 2025

Posters & Demos



Monday

- Realtime-Rendering of Dynamic Scenes with Neural Radiance Fields
- Creating Virtual Environments with 3D Gaussian Splatting: A Comparative Study

Tuesday

- Human-in-the-Loop Gaussian Model Enhancement with Mobile Robotic Re-Capture
- **DimSplat: A Real-Time Diminished Reality System for Revisiting Environments Using Gaussian Splats in Mobile WebXR** by Kristoffer Waldow, *et al.* 🧡
- GaussianShopVR: Facilitating Immersive 3D Authoring using Gaussian Splatting in VR
- LIVE-GS: LLM Powers Interactive VR by Enhancing Gaussian Splatting

Wednesday

- Extending Gaussian Splatting to Audio: Optimizing Audio Points for Novel-view Acoustic Synthesis

Demo

- LLM-powered Gaussian Splatting in VR interactions

Pipeline

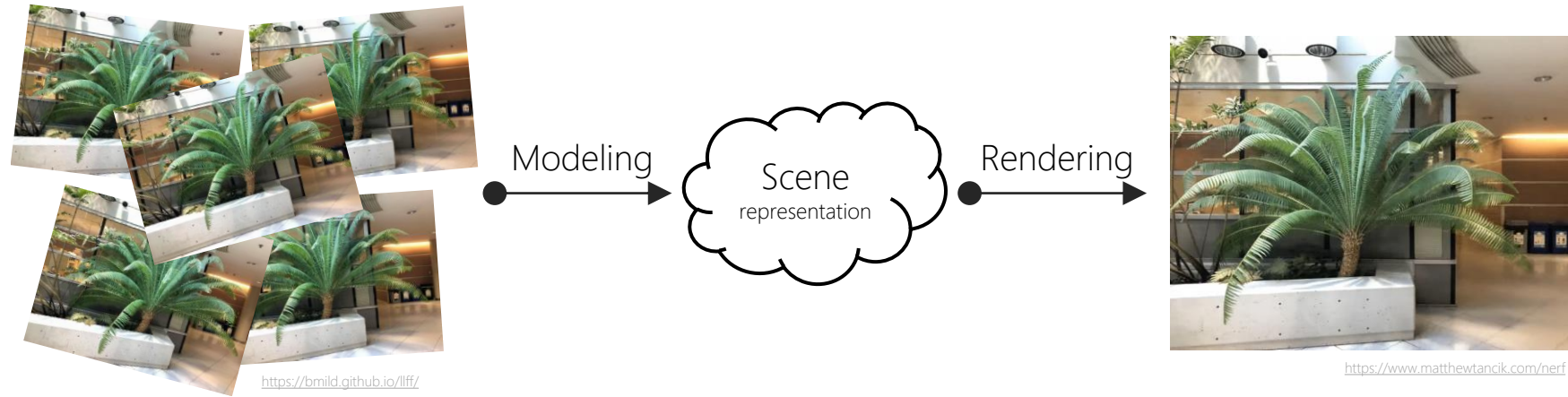


Image-Based & Neural Rendering Continuum

Modified from H.-Y. Shum, S.-C. Chan, and S. B. Kang, “Image-Based Rendering,” Springer (2007)

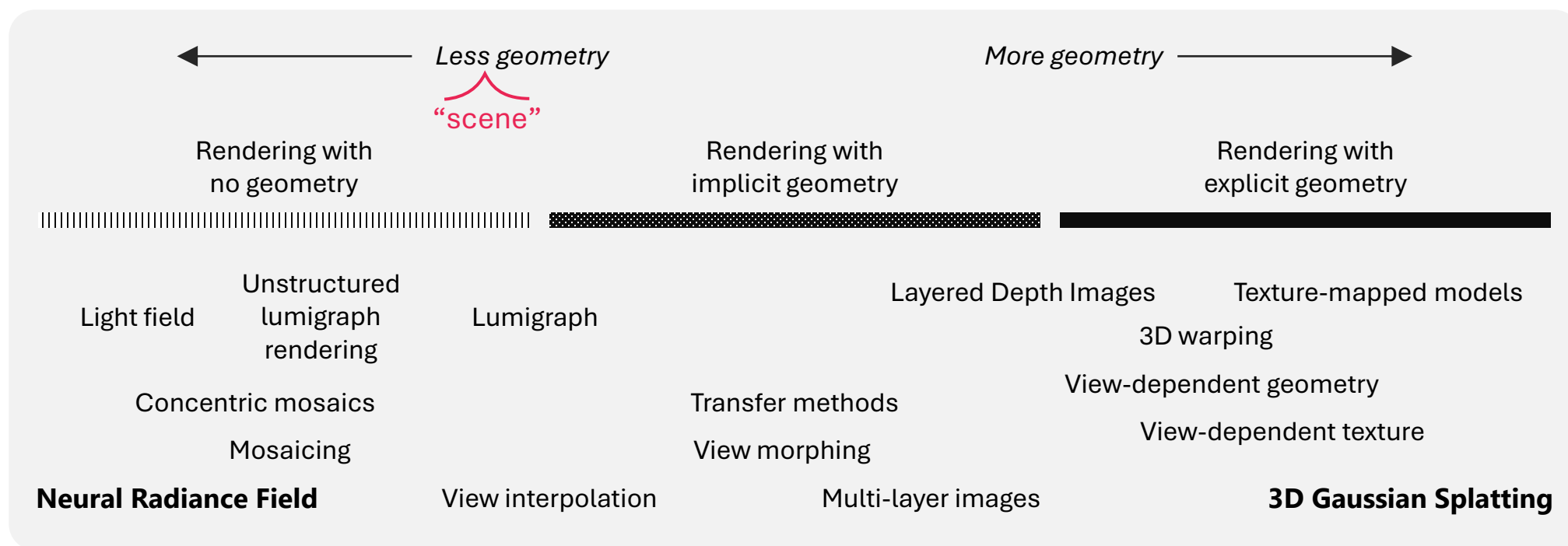


Image-Based Rendering (IBR)

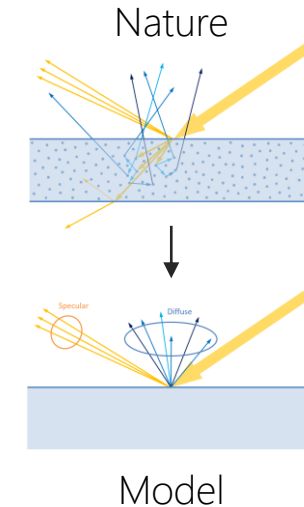
More photographs instead of precise scene models

Geometry (surface locations, visibility, deformation, etc.)
Surface properties (albedo, reflection, BRDF, etc.)

Recently, often referred to as **view synthesis**

Significantly reduced modeling effort, but still visually convincing

that comes with many known limitations...

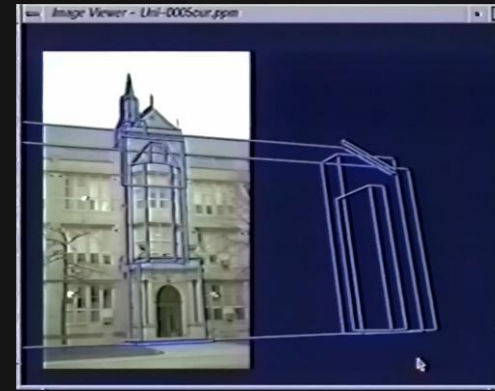


Photogrammetry/scanning falls short in specular, hairs, transparency, complex sub-surface scattering, dynamics, and more...

View-Dependent Texture Mapping (VDTM)

P. Debevec, Modeling and Rendering Architecture from Photographs, Ph.D. Thesis, UC Berkley, 1996.

- Each surface maintains a list of reference views, from which it is visible
- For rendering current view, reference views are projected onto the surface
- Pixels with overlaps are blended depending on proximity of current view to the reference views
- GPU-based projective texture mapping for further efficiency



GUI for manual modeling and camera/photograph registration

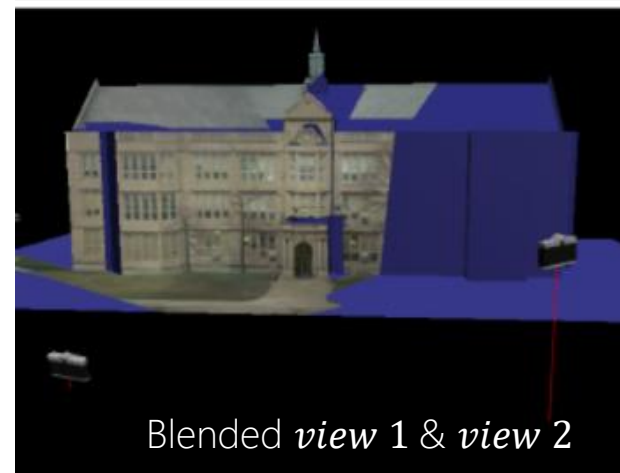
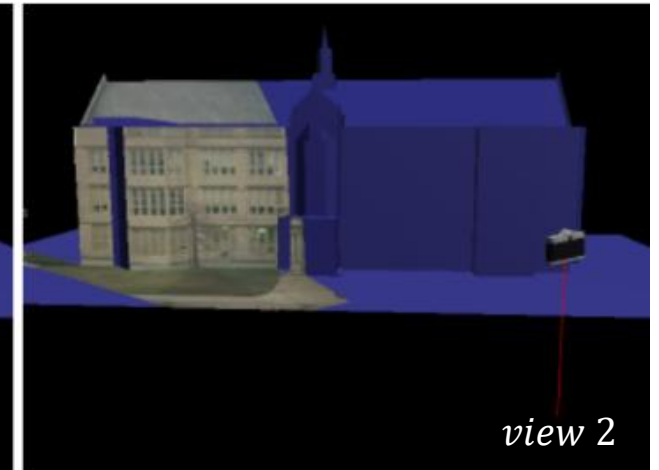
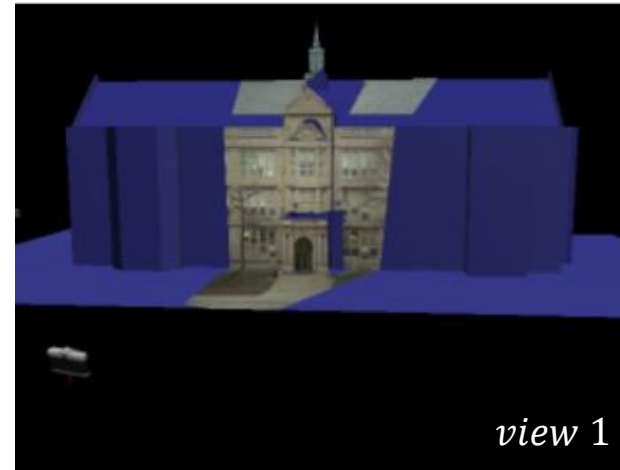
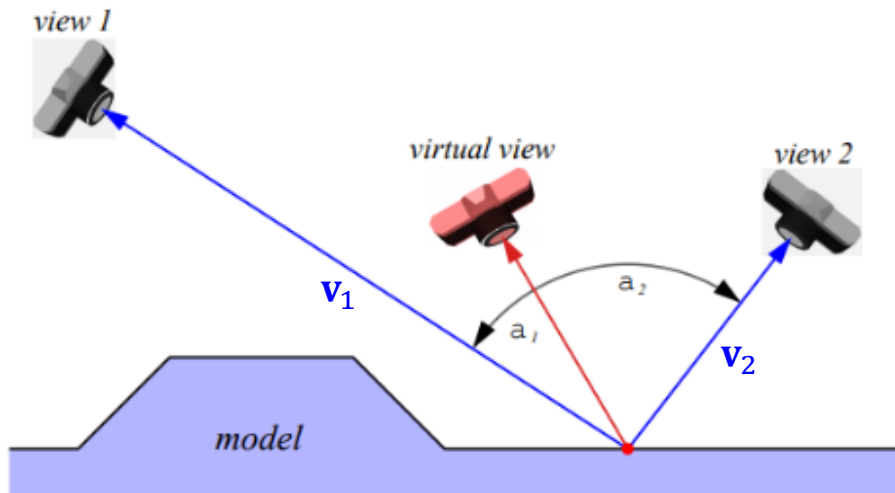
Camera/photograph registered in the scene



Blending Photographs

P. Debevec, Modeling and Rendering Architecture from Photographs, Ph.D. Thesis, UC Berkley, 1996.

- Calc. \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}
- Calc. a_1 and a_2
- Calc. weights (w_1 and w_2)
- Blend *view 1* and *view 2*
 - *virtual view* = $w_1 * \text{view 1} + w_2 * \text{view 2}$



Limitation in IBR



- Choices are
 - Poor 3D reconstruction + More images → More storage
 - Accurate 3D reconstruction + Fewer images → More computation
- } Not preferable to XR
- Select k „nearest“ views per vertex
 - View switching artifacts
 - Views selection during photographing and rendering with care!
 - No defacto-standard solutions
 - Very few open source projects (especially, in XR)

Differentiable Rendering Pipeline

$$R(\theta) = I'$$

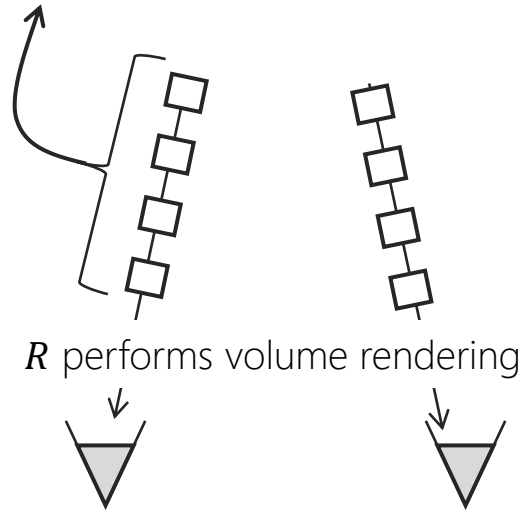
- A set of scene parameters θ is given
 - θ can be points, voxel, mesh, implicit (or network parameters), Gaussians, etc.
- A **differentiable renderer** R calculates an image I' from θ
- Calculate the loss between the rendered image I' and its ground truth I
 - Auto-grad backpropagates to reflect the loss to the scene parameters θ

R provides an “interpretation” to θ so that θ can represent a scene and optimization framework tries to find the best θ through evaluations of generated image I' by comparing it with its ground truth I (i.e., $\text{Loss}(I', I)$), that is **analysis by synthesis**

Differentiable Rendering Pipeline

$$R(\theta) = I'$$

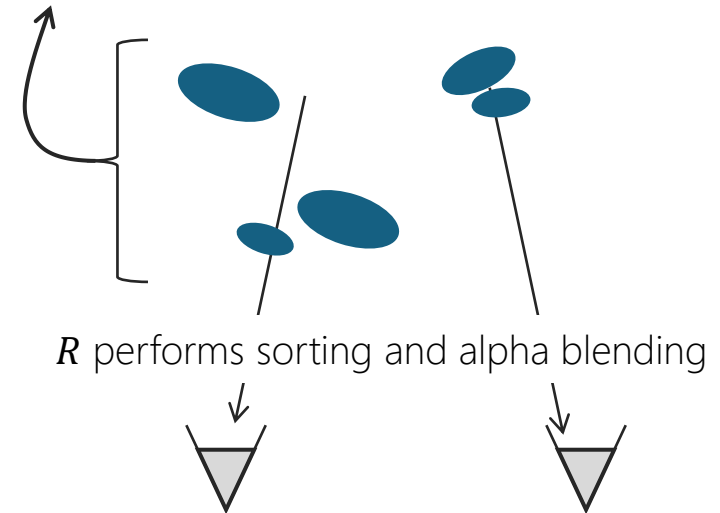
θ is a set of network weights to infer RGB+ σ (density) values



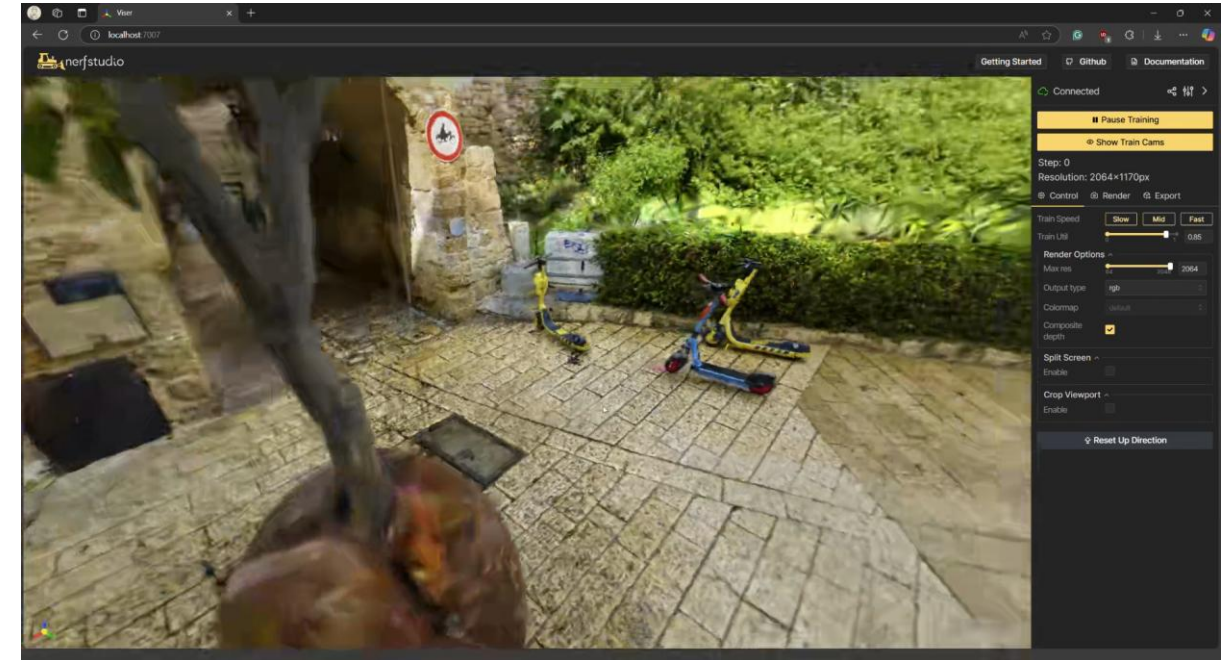
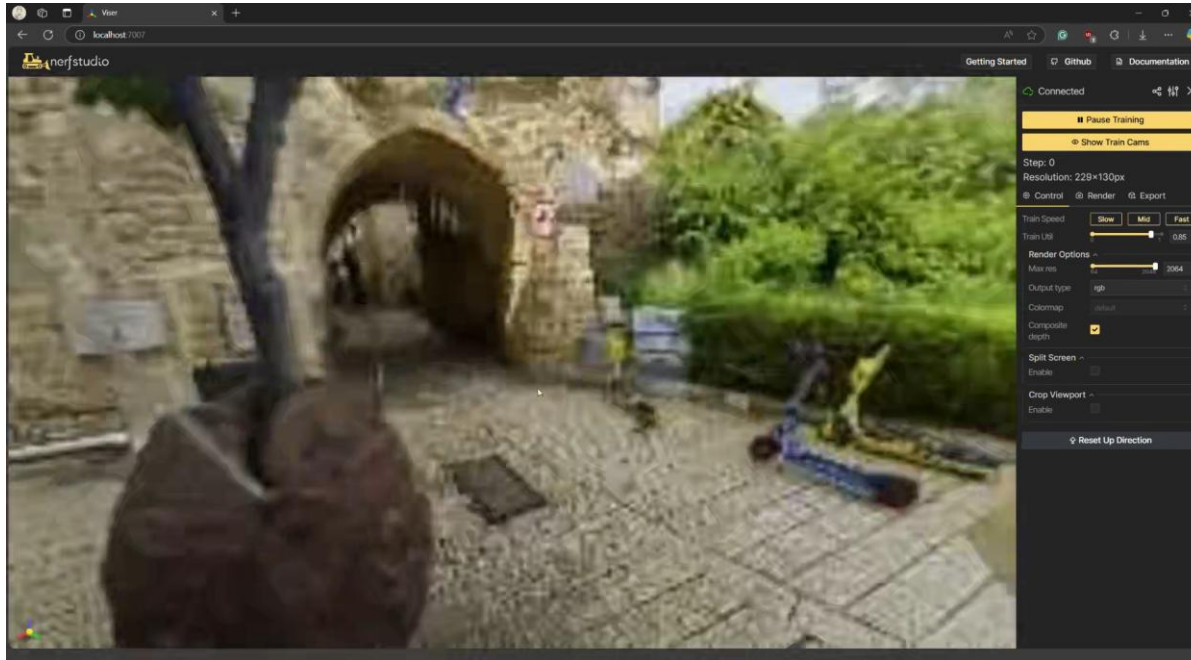
3D Gaussian Splatting

Neural Radiance Fields (NeRF)

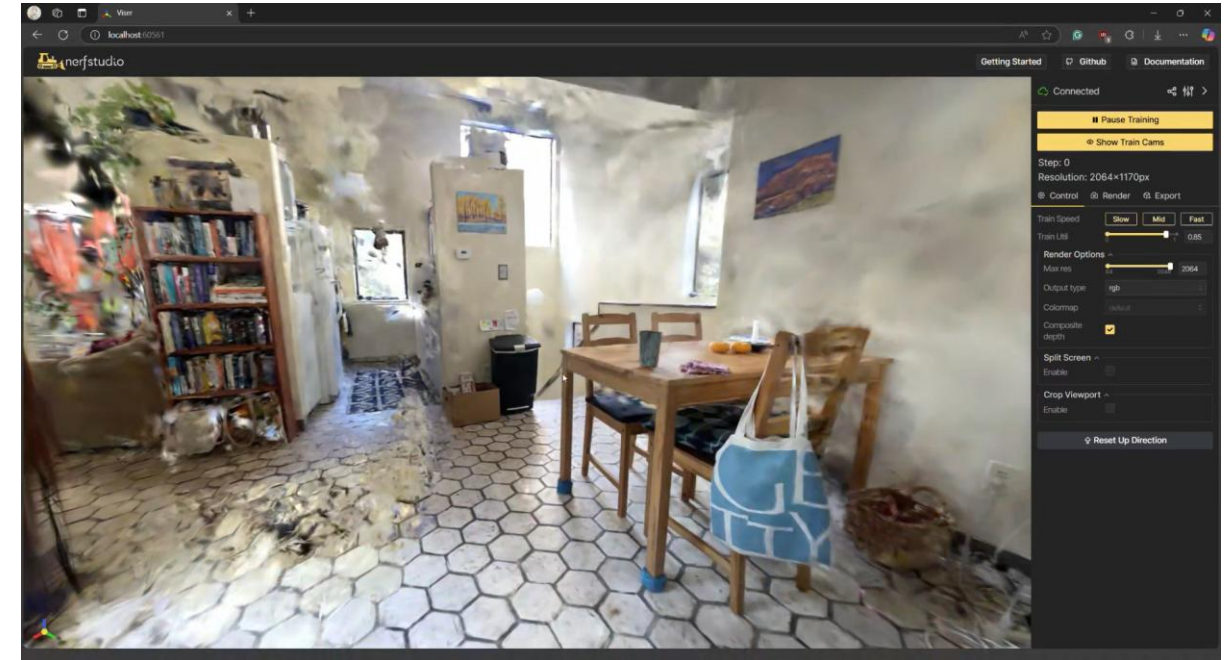
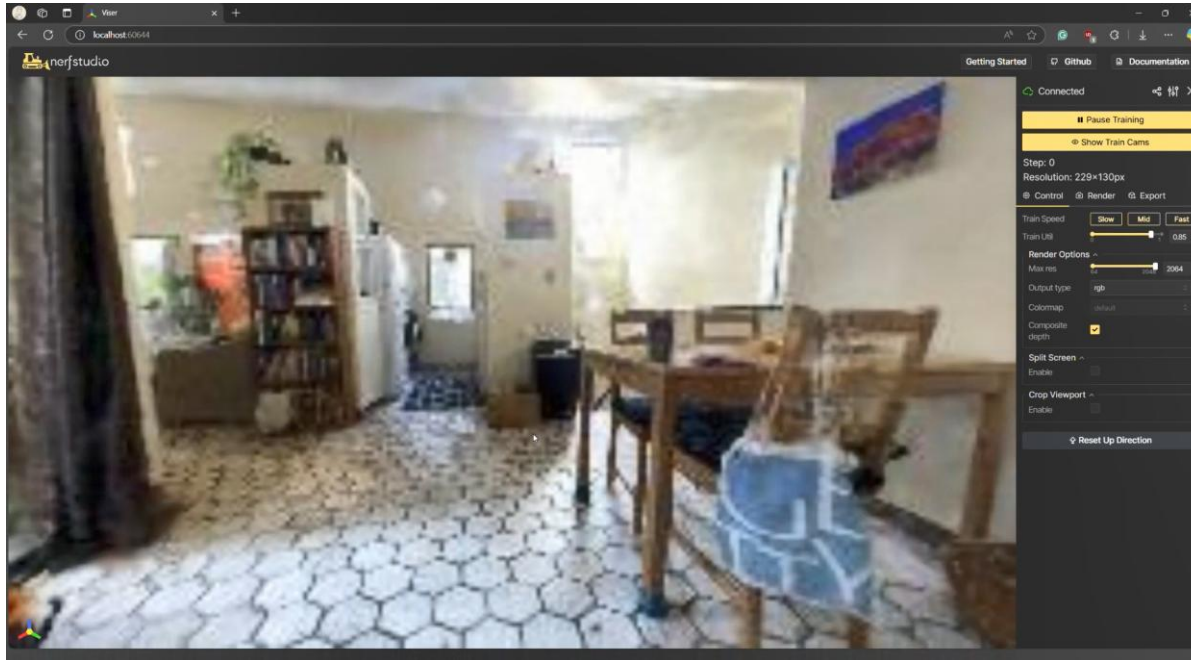
θ is a set of Gaussians (a "rich" point cloud)



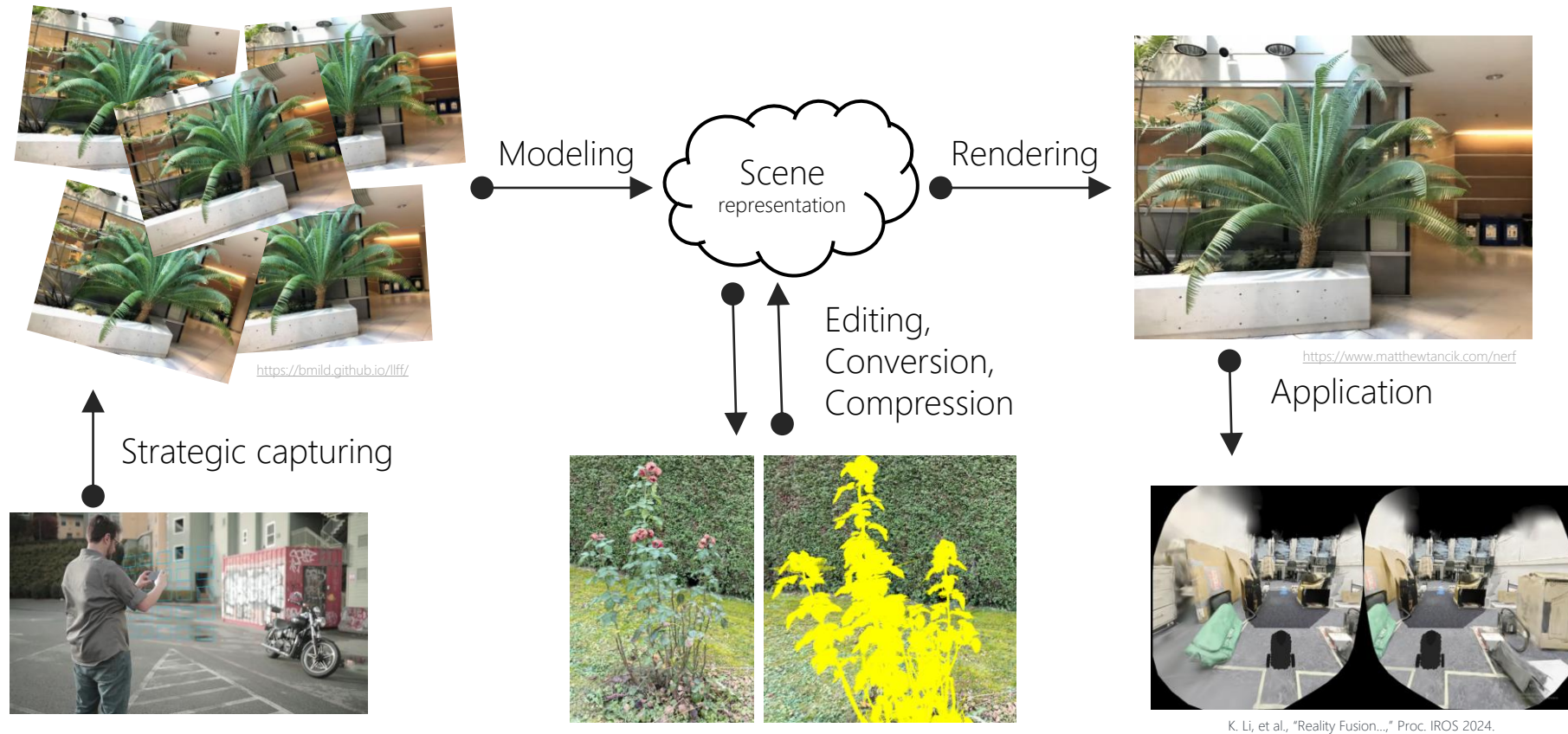
NeRF vs. 3DGS



NeRF vs. 3DGS





Pipeline



Capture Tools



- Scaniverse 
 - 3DGS (local processing)
 - iOS (with LiDAR) / Android
 - Real-time 3DGS on iOS
 - Free of charge
- Polycam 
 - 3DGS (server processing, up to 100 images)
 - iOS (with LiDAR) / Android
- COLMAP / GLOMAP
 - Defacto standard for research
 - Python interface

Next-up



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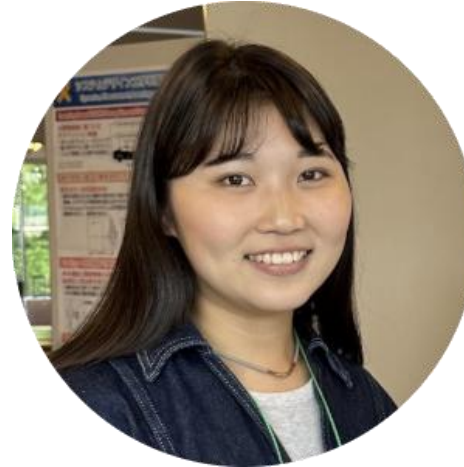
Next-up



Ke Li

University of Hamburg

Neural Radiance Fields
Immersive-ngp
(Unity + VR + Instant-ngp)



Mana Masuda

Keio University

3D Gaussian Splatting
UnityGaussianSplatting
(Unity + VR + 3DGS)

Future Directions



Topics around Radiance Fields

- **Interactive Experiences:** Education, Training, Telepresence / Collaboration / Avatar
- **User-centric rendering:** Foveated Rendering / VST-HMD
- **Benchmarking:** Quality Assessment / Toolkit
- **Multi-modal:** Haptics / Audio
- **Content Editing:** Style Transfer / Style Edit / Relighting / Diminished Reality
- **Content Generation:** Text to 3D (content / scene) / Content Generation
- **Spatial Registration:** Tracking / SLAM / Bundle adjustment
- **Dynamic Capture:** 4D / Performance / Dynamics
- **Optimization Techniques:** Faster Rendering / Few-shot / Streaming / Compression